

## **LISTING OF CLAIMS**

This listing of claims will replace all prior versions, and listings, of claims in the application:

1. (Canceled)
2. (Canceled)
3. (Canceled)
4. (Previously Presented)      A spreader system for lifting containers comprising:
  - a spreader frame;
  - at least one telescopic beam telescopically movable in said spreader frame;
  - at least one locking member positioned between said spreader frame and said at least one telescopic beam for stopping the telescopic movement of said at least one telescopic beam in relation to said frame, said locking member including a locking point comprising a drive ramp and a form-locking groove, and a locking part including a locking roller fitting into the form-locking groove and a locking spring locking the locking roller in said form-locking groove the compression force of the locking spring being adjustable, with a magnet;
  - at least one twistlock in said at least one telescopic beam having a locked and unlocked position;
  - a joint multi-rope system for performing the telescopic movement of said at least one telescopic beam and also for actuating said at least one twistlock;
  - at least one actuator operating said joint multi-rope system; and
  - a control system for supervising and controlling the operations of said at least one actuator and said joint multi-rope system.

5. (Canceled)

6. (Currently Amended) The spreader system according to claim 4 ~~5~~, wherein said actuator generates an external force directed to the telescopic beams, said external force being partly neutralized by the elasticity of the multi-rope system and partly neutralized by the interaction between the locking point of the telescopic beams and the locking unit of the frame.

7. (Canceled)

8. (Canceled)

9. (Canceled)

10. (Canceled)

11. (Previously Presented) A spreader system for lifting containers comprising:

a spreader frame including a locking unit disposed thereon;

at least one telescopic beam telescopically movable in said spreader frame, said beam including at least one locking point disposed thereon, said locking point being engageable with said locking unit of said frame for releasably locking said at least one telescopic beam in relation to said frame;

at least one twistlock in said at least one telescopic beam having a locked and unlocked position;

a joint multi-rope system for performing the telescopic movement of said at least one telescopic beam and also for actuating said at least one twistlock;

at least one actuator operating said joint multi-rope system, said actuator applying a first rope force on said multi-rope system for telescopically moving said beam in said

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spreader frame, a second rope force on said multi-rope system for moving said locking point of said beam into engagement with said locking unit of said frame, and a third rope force on said multi-rope system for actuating said twistlock when said locking point of said beam is engaged with said locking unit of said frame, said third rope force being greater than said second rope force and said second rope force being greater than said first rope force; and

a control system for supervising and controlling the operations of said at least one actuator and said joint multi-rope system.